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```
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Engineering with ...
functionp=newtonPoly(a,xData,x) % Returns
value of Newton's polynomial at x.
%USAGE:p=newtonPoly(a,xData,x) % a =
coefficient array of the polynomial; % must
be computed first by newtonCoeff. % xData = x-
coordinates of data points. n =
length(xData); p = a(n); fork=1:n-1; p = a(n-1)
k) + (x - xData(n-k))*p; end.
```

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and hence it is a need to seek approximate solutions by means of numerical methods.

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Delay. differential equations (DDEs) form an important class of dynamical systems. They often arise.

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/ 21. Order Taylor Series functions shown below in the Matlab program f1 f2 f4 Note the 2nd Solution manual numerical methods engineering a solution manual for

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Ingredients: Broken wheat: 1 cup Milk: 3 cups (pasturised or boiled) Jaggery (traditional unrefined cane sugar) - 2 cups (or according to taste) Ghee: cup Water: 3 cups Cashews: cup Raisins (draksha or dry grapes): cup Almonds: cup Cardamom: (powdered) - tea spoon Preparation Method: Heat a frying pan on Page 17/18

stove.

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