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control uses sensor data (e.g. brightness, temperature, or velocity) to adjust or correct actuation (e.g. steering angle, motor acceleration, or heater output), and you use it all the time, like when you steer a bicycle, catch a ball, or stand upright.

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components of the controller should and shouldn't be used. The physics of an elevator are simulated to allow you the opportunity to write control software and see how it performs.

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